# 120-22-UA2 Graphic Operator Panel & Programmable Logic Controller

24VDC, 12 pnp/npn digital inputs, 2 universal inputs\*, high-speed counter/shaft encoder input, 10 transistor outputs, 2 analog outputs, I/O expansion port, 2 RS232/RS485 ports

Power supply	24VDC
Permissible range	20.4VDC to 28.8VDC with less
	than 10% ripple
Maximum current	210mA@24VDC (pnp inputs)
consumption	315mA@24VDC (npn inputs)
i	
Digital inputs	12 pnp (source) or npn (sink)
	inputs. See Note 1.
Nominal input voltage	24VDC.
	See Note 2.
Input voltages for pnp (source)	0-5VDC for Logic '0'
,	17-28.8VDC for Logic '1'
Input voltages for npn (sink)	17-28.8VDC/<2mA for Logic '0'
	0-5VDC/>6mA for Logic '1'
Input current	8mA@24VDC
Input impedance	3ΚΩ
Response time	10mS typical
(except high-speed inputs)	
Galvanic isolation	None
Input cable length	Up to 100 meters, unshielded
High-speed counter	Specifications below apply when
	inputs are wired for use as a high-
	speed counter input/shaft
	encoder. See Note 3 and 4.
Resolution	32-bit
Input frequency	10kHz max.
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Notes:

Minimum pulse

1. All 12 inputs can be set to pnp (source) or npn (sink) via a single jumper and appropriate wiring.

40µs

- npn (sink) inputs use voltage supplied from the controller's power supply.
  Input #0 can function as either high-speed counter or as
- part of a shaft encoder. In each case, high-speed input specifications apply. When used as a normal digital input, normal input specifications apply.
- Input #1 can function as either counter reset, or as a normal digital input; in either case, specifications are those of a normal digital input.

This input may also be used as part of a shaft encoder.

In this case, high-speed input specifications apply.

# Power supply, pnp (source) inputs



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Note:

To avoid electromagnetic interference, mount the controller in a metal panel/cabinet and earth the power supply. Earth the power supply signal to the metal using a wire whose length does not exceed 10cm. If your conditions do not permit this, do not earth the power supply.

## npn (sink) inputs



pnp (source) high-speed counter



# npn (sink) high-speed counter



Shaft encoder





\* Certain inputs can function as normal digital inputs, analog inputs or thermocouple inputs, in accordance with jumper settings and wiring connections.



- Unused pins should not be connected. Ignoring this directive may damage the controller.
- Improper use of this product may severely damage the controller.
- Refer to the controller's User Guide regarding wiring considerations.
- Before using this product, it is the responsibility of the user to read the product's User Guide and all accompanying documentation.

# **Universal Inputs**

Analog Inputs	Two 14-bit, multi-range inputs:
	0-10V, 0-20mA, 4-20mA
	See Note 1
Conversion method	Voltage to Frequency
Input impedance	>400K $\Omega$ for voltage
	500 $\Omega$ for current
Isolation	None
Resolution (except 4-20mA)	14-bit (16384 units)
Resolution at 4-20mA	3277 to 16383 (13107 units)
Conversion time	100mSec minimum
	(according to filter type)
Absolute max. rating	±15V for voltage
	±30mA for current
Linearity error	0.04% max. of full scale
Error limit	0.4% of input value
Status indication	Yes, see Note 2

Notes:

1. Inputs #8 and #10 can each function as an analog input, related to signal 0V, in accordance with jumper settings and wiring connections.

2. The analog value can also indicate faults, as shown below:

Value	Possible Cause	
-1	Input value deviates slightly below the input range.	
16384	Input value deviates slightly above the input range	
32767	Input value deviates greatly above or below the input range.	

### Voltage / Current connection



Notes:

a. Shields should be connected at the signals' source.

b. The 0V signal of the analog input must be connected to the controller's 0V.

# **Current connection**



Notes:

a. Shields should be connected at the signals' source.b. The 0V signal of the analog input must be connected to the controller's 0V.

Thermocouple inputs	2 differential inputs.
	See Note 1.
Input type	Thermocouple
Input ranges	As shown in the table below
Isolation	None
Conversion method	Voltage to Frequency
Resolution	0.1°C / 0.1°F
Conversion time	100mSec minimum
	(according to filter type)
Input impedance	>10MΩ
Cold junction compensation	local, automatic
Cold junction compensation error	±1.5°C / ±2.7°F maximum
Absolute maximum rating	±0.6 VDC
Linearity error	0.04% max. of full scale
Error limit	0.4% of input value
Status indication	None
Warm-up time	1/2 hour typically,
-	±1°C / ±1.8°F repeatability

Notes:

1. Thermocouple #0: use Input #10 as positive input & Input #9 as negative input. Thermocouple #1: use Input #8 as positive input & Input #7 as negative input. To use inputs as thermocouple, set the relevant jumpers and use appropriate wiring.

### **Table 1: Input Ranges**

Туре	Temperature range	Wire color		
		ANSI (USA)	BS 1843 (UK)	
mV	-5 to 56mV	-	-	
В	200 to 1820°C	+ Grey	+ None	
	(300 to 3276°F)	- Red	- Blue	
E	-200 to 750°C	+ Violet	+ Brown	
	(-328 to 1382°F)	- Red	- Blue	
J	-200 to 760°C	+ White	+ Yellow	
	(-328 to 1400°F)	- Red	- Blue	
K	-200 to 1250°C	+ Yellow	+ Brown	
	(-328 to 2282°F)	- Red	- Blue	
N	-200 to 1300°C	+ Orange	+ Orange	
	(-328 to 2372°F)	- Red	- Blue	
R	0 to 1768°C	+ Black	+ White	
	(32 to 3214°F)	- Red	- Blue	
S	0 to 1768°C	+ Black	+ White	
	(32 to 3214°F)	- Red	- Blue	
Т	-200 to 400°C	+ Blue	+ White	
	(-328 to 752°F)	- Red	- Blue	

### Thermocouple connection



Note:

Shields should be connected at the signals' source.



Digital outputs	10 pnp (source) outputs
	24VDC
Output type	P-MOSFET (open drain)
Isolation	None
Output current	0.5A max.
	Total current: 3A max.
Max. frequency for normal outputs	50Hz (resistive load)
	0.5Hz (inductive load)
High speed output maximum	2kHz (resistive load)
frequency	See Note 1.
Short circuit protection	Yes
Short indication	by software
On voltage drop	0.5VDC maximum
Power supply for outputs	
Operating voltage	20.4 to 28.8VDC
Nominal operating voltage	24VDC

Note:

1. Output #0 and Output #1 may be used as high-speed outputs.

# **Digital Outputs connection**



Analog outputs	Two 12-bit analog outputs:
	0-10V, 4-20mA, See note 1.
Load impedance	1kΩ minimum—voltage
	500Ω maximum—current
Galvanic isolation	None
Resolution	12-bit (4096 units)
Conversion time	Synchronized to scan time
Linearity error	±0.1%
Operational error limits	±0.2%

Note:

1. Each analog output range is defined by wiring, jumpers and within the controller's software.

# Analog outputs connection



#### Notes:

- a. Shields should be earthed, connected to the earth of the cabinet.
- b. The 0V signal of the analog outputs must be the same 0V used by the controller's power supply.

Graphic Display	STN, LCD display
Illumination backlight	LED, yellow-green,
	software-controlled
Display resolution	128x64 pixels
Keypad	Sealed membrane
Number of keys	16
Program	
Application memory	448K
Memory Bits (coils)	2048
Memory Integers (registers)	1600
Long Integers (32 bit)	256
Double Word (32 bit unsigned)	64
Floats	24
Timers	192
Counters	24
Data Tables	120K (RAM) / 64K (FLASH)
HMI displays	Up to 255
Execution time	0.8µs for bit operations

RS232/RS485 serial ports	Used for: • Application Download/Upload • Application Testing (Debug) • Connect to GSM or standard telephone modem: - Send/receive SMS messages - Remote access programming • RS485 Networking
RS232 (see note)	2 ports
Galvanic isolation	None
Voltage limits	±20V
RS485 (see note)	2 ports
Input voltage	-7 to +12V differential max.
Cable type	Shielded twisted pair, in compliance with EIA RS485
Galvanic isolation	None
Baud rate	110 – 57600 bps
Nodes	Up to 32

Note: RS232/RS485 is determined by jumper settings and wiring. Refer to the controller's User Guide regarding communications.

Up to 128 additional I/Os,
including digital & analog I/Os,
RTD and more.
Real-time clock functions
(Date and time).
7 years typical battery back-up for
RTC and system data.
Coin type, 3V lithium battery,
CR2450
280g. (9.8oz)
0 to 50°C (32 to 122°F)
-20 to 60°C (-4 to 140°F)
5% to 95% (non-condensing)
DIN-rail mounted (IP20/NEMA1)
Panel mounted (IP65/NEMA4X)





# Important:

Incompatible jumper settings and wiring connections may severely damage the controller.

### JP2, JP3, JP6, JP8 Input #9 and Input #10 (universal input no. 0)

To use as	JP2	JP3	JP6	JP8
	for Input#10	for Input#9	for Input#10	for Input#10
Normal digital inputs	А	A	А	В
Thermocouple input* (See Note 1)	В	В	А	В
Analog input - voltage (see Note 3)	В	A See Note 2	В	A
Analog input - current (see Note 3)	В	A See Note 2	В	В

Notes:

1. Thermocouple input is between Input#10 (T+) and Input#9 (T-).

2. When using Input#10 as analog input, Input#9 can be used as normal digital input.

3. Analog inputs are related to signal 0V.

## JP4, JP5, JP7, JP9 Input#7 and Input#8 (universal input no. 1)

To use as	JP4	JP5	JP7	JP9
	for Input#8	for Input#7	for Input#8	for Input#8
Normal digital inputs	А	A	А	В
Thermocouple input* (See Note 1)	В	В	A	В
Analog input - voltage (see Note 3)	В	A See Note 2	В	A
Analog input - current (see Note 3)	В	A See Note 2	В	В

Notes:

- 1. Thermocouple input is between Input#8 (T+) and Input#7 (T-).
- 2. When using Input#8 as analog input, Input#7 can be used as normal digital input.
- 3. Analog inputs are related to signal 0V.

#### JP10 Input type (for all digital inputs) see Note 1

To use as	JP10
npn (sink)	А
pnp (source)*	В

#### Note:

 Inputs# 0-6, input #11 and #7-10 when these are set as normal digital inputs.

\*Default factory setting



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# V120-22-UA2 I/O Jumper Settings

# JP12 Analog output #0

To use as	JP12
Voltage*	A
Current	В

# JP11 Analog output #1

To use as	JP11
Voltage*	A
Current	В

# \*Default factory setting



### In this figure, the jumper settings will cause the inputs and the analog outputs to function as follows:

Universal Input #0 (Input #10): Voltage input, related to 0V

Universal Input #1 (Input #7 and Input #8): Termocouple input

Input#9: Normal npn, 24VDC digital input

Input#0 to Input #6 and input #11: npn, 24VDC digital inputs.

(Note that these inputs can only function as normal digital inputs.)

Analog output #0: Voltage output

Analog output #1: Current output

Note: Jumper #1 is reserved - do not use.

# Opening the controller's enclosure

- 1. Turn power off before opening the controller.
- 2. Locate the 4 slots on the sides of the enclosure.
- 3. Using the blade of a flat-bladed screwdriver, gently pry off the back of the controller as shown in the figure below, exposing the controller's board.

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